## A Test for Two Poisson Processes in the Presence of Background Events

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### Overview

- Description of the original problem
- Features of the problem
- Methodology and formulas
- Test run A: non-conditioned inference
- Test run B: conditional inference
- Results and conclusions
- Final Thoughts

# The original problem

- Two arrays for detecting cosmic rays:
  - High-Resolution Fly's Eye (HiRes), Utah
  - Akeno Giant Airshower Array (AGASA), Japan
- 1996: AGASA reports observing clusters of ultrahigh energy (over 4x10<sup>19</sup>eV) particles.
- 1997-2003: HiRes detects similar clusters of rays.
- Are these particles coming from the same cosmic sources?

# The original problem (cont.)

- Some of the "events" detected by the arrays is just background noise.
- The hits on both detectors are an unknown mix of background events and "real" events.
- Simulations have yielded estimates for the expected number of background events at AGASA and HiRes.
- Are the sources of AGASA's real events the same as the sources of HiRes's?
- Do real events come into the HiRes and AGASA detectors at the same rate?

# Declaring variables

- Constants:
  - T<sub>1</sub>: time that the HiRes detector is open
  - T<sub>2</sub>: time that the AGASA detector is open
  - $\mu_{1f}$ : expected number of background events at HiRes
  - $\mu_{2f}$ : expected number of background events at AGASA
- Parameters:
  - $f_{1r}$ : frequency of non-background events at HiRes
  - $f_{2r}$ : frequency of non-background events at AGASA
  - $f_{0r}$ : frequency of non-background events if  $f_{1r} = f_{2r}$ .
  - $T_1 f_{1r} + \mu_{1f}$ : expected number of total events at HiRes
  - $T_2 f_{2r} + \mu_{2f}$ : expected number of total events at AGASA
- Data:
  - $x_1$ : number of events detected at HiRes
  - $x_2$ : number of events detected at AGASA

# The model

- Model:
  - $x_1$  and  $x_2$  are independent random variables
  - $x_1$  has a Poisson distribution with mean  $T_1f_{1r} + \mu_{1f}$ .
  - $x_2$  has a Poisson distribution with mean  $T_2f_{2r}+\mu_{2f}$
- Hypotheses:
  - The null hypothesis is  $H_0: f_{1r} = f_{2r} = f_{0r}$ .
  - The alternative is two-sided.
- Under the alternative,  $f_{1r}$  and  $f_{2r}$  can be estimated separately.
  - If the number of events  $x_1$  is less than the expected number of background events  $\mu_{1f}$ , then the MLE for  $f_{1r}$  is 0.
  - If the number of events  $x_2$  is less than the expected number of background events  $\mu_{2f}$ , then the MLE for  $f_{2r}$  is 0.
  - The MLE for  $f_{1r}$  is the maximum of 0 and  $(x_1 \mu_{1f})/T_1$ .
  - The MLE for  $f_{2r}$  is the maximum of 0 and  $(x_2 \mu_{2f})/T_2$ .

### Point estimation

• To get the MLE for f<sub>0r</sub> under the null, we maximize the joint Poisson likelihood:

$$L_{0}(x_{1}, x_{2}, f_{0r}) = e^{-(T_{1}+T_{2})f_{0r}-\mu_{1f}-\mu_{2f}} \frac{(T_{1}f_{0r}+\mu_{1f})^{x_{1}}}{x_{1}!} \frac{(T_{2}f_{0r}+\mu_{2f})^{x_{2}}}{x_{2}!} \quad \text{and} \\ \ell_{0}(x_{1}, x_{2}, f_{0r}) = -(T_{1}+T_{2})f_{0r}-\mu_{1f}-\mu_{2f} \\ + x_{1}\log(T_{1}f_{0r}+\mu_{1f}) + x_{2}\log(T_{2}f_{0r}+\mu_{2f}) - \log(x_{1}!x_{2}!).$$

• The MLE for  $f_{0r}$  is the maximum of 0 and

$$\begin{split} \hat{f}_{0\mathbf{r}} &= \frac{1}{2} \frac{x_1 + x_2}{T_1 + T_2} - \frac{1}{2} \frac{\mu_{2f} T_1 + \mu_{1f} T_2}{T_1 T_2} \\ &+ \frac{\sqrt{((T_1 + T_2)(\mu_{1f} T_1 + \mu_{2f} T_2) - (x_1 + x_2)T_1 T_2)^2}}{+ 4(T_1 + T_2)T_1 T_2 \left(x_1 T_1 \mu_{2f} + x_2 T_2 \mu_{1f} - (T_1 + T_2) \mu_{1f} \mu_{2f}\right)}{2T_1 T_2 (T_1 + T_2)} \end{split}$$

## Looking at the formulas

- Three lines partition the outcome space into 6 zones.
  - $f_{1r} = 0 \text{ if } x_1 < \mu_{1f}.$
  - $f_{2r} = 0 \text{ if } x_2 < \mu_{2f}.$
  - $f_{0r} = 0 \text{ if } T_1 \mu_{2f} x_1 + T_2 \mu_{1f} x_2 < (T_1 + T_2) \mu_{1f} \mu_{2f}.$
  - The three lines meet at a single point.
- The estimate for  $f_{0r}$  is  $(x_1+x_2)/(T_2+T_2)$  minus a correction term for the interference of  $\mu_{1f}$  and  $\mu_{2f}$ .
- If  $\mu_{1f} = 0$  and  $\mu_{2f} = 0$ , if there is no background noise, then we get exactly  $(x_1+x_2)/(T_2+T_2)$ .

#### The likelihood ratio statistic

• Let  $l_0(x_1, x_2, f_{0r})$  be the log-likelihood under the alternative. Let  $l_A(x_1, x_2, f_{1r}, f_{2r})$  be the log-likelihood under the alternative. The likelihood ratio statistic is

$$\begin{split} LR &= 2\left(\ell_A\left(x_1, x_2, \hat{f}_{1r}, \hat{f}_{2r}\right) - \ell_0\left(x_1, x_2, \hat{f}_{0r}\right)\right) \\ &= 2 \begin{pmatrix} -T_1 \hat{f}_{1r} - T_2 \hat{f}_{2r} - \mu_{1f} - \mu_{2f} \\ + x_1 \log\left(T_1 \hat{f}_{1r} + \mu_{1f}\right) + x_2 \log\left(T_2 \hat{f}_{2r} + \mu_{2f}\right) - \log\left(x_1 | x_2 | \right) \\ + (T_1 + T_2) \hat{f}_{0r} + \mu_{1f} + \mu_{2f} \\ - x_1 \log\left(T_1 \hat{f}_{0r} + \mu_{1f}\right) - x_2 \log\left(T_2 \hat{f}_{0r} + \mu_{2f}\right) + \log\left(x_1 | x_2 | \right) \end{pmatrix} \\ &= 2 \begin{pmatrix} x_1 \log\left(\frac{T_1 \hat{f}_{1r} + \mu_{1r}}{T_1 \hat{f}_{0r} + \mu_{1r}}\right) - T_1 \hat{f}_{1r} - T_2 \hat{f}_{2r} \\ + x_2 \log\left(\frac{T_2 \hat{f}_{2r} + \mu_{2r}}{T_2 \hat{f}_{0r} + \mu_{2r}}\right) + (T_1 + T_2) \hat{f}_{0r} \end{pmatrix} \end{split}$$

### Test data set

- These numbers were based on conversations with Professor Belz in the Department of Physics at the University of Montana.
- The difference in the time exposures cancel out the difference in the sizes of the arrays, so we can let  $T_1=T_2=1$ .
- According to simulations,  $\mu_{1f}$ =3.6 and  $\mu_{2f}$ =6.4.
- There were  $x_1=6$  events at HiRes and  $x_2=13$  events at AGASA.
- The MLEs are  $f_{1r}=2.4$ ,  $f_{2r}=6.6$ , and  $f_{0r}=6.923737$ .
- The likelihood ratio statistic is LR=2.312918.

#### Test Run A: unconditional inference

- Each possible data pair  $(x_1, x_2)$  has an  $f_0$  and a LR $(x_1, x_2)$ .
- We'd like to use these  $LR(x_1,x_2)$  to obtain a p-value.
- Let  $f_{0rdata}$  be the data pair's estimate for  $f_{0r}$ . Let  $LR_{data}$  be the data pair's likelihood ratio statistic.
- We use the distribution for  $(x_1, x_2)$  over the whole quarter-plane.
- Our p-value is the sum of the probabilities of all the  $(x_1, x_2)$  with higher LR's:  $\Sigma_{LR(x_1, x_2) \ge LRdata} P(x_1, x_2 | f_{0rdata})$ .
- With the test data, the p-value is 0.2218632.
- Each possible data set has its own  $f_0$ , so each data set gets its own p-value based on its own distribution under the null.
- If the null is true, then the distribution for the p-value should be Uniform(0,1), plus or minus the discrete nature of the model.

## The cumulative density function

- This is the distribution of the p-value if the null is true and  $f_{0r}$  is the data's  $f_{0r}$ .
- For any α, the probability of rejecting is always greater than α.
- We expect some of this, since P(LR=0)>0, but this is bad.



# Focusing on practical $\alpha$

- We can see the discretization.
- Data pairs that are CLEARLY not significant are still not significant.



# Test Runs B: conditional inference

- This time, we're going to try conditioning on  $f_{0r}$ .
- We can't limit ourselves to data pairs with the exact same  $f_{0r}$  as our data's. There won't be enough other data pairs. There might not be any.
- We can try choosing a percentage w, and then limit ourselves to  $(x_1,x_2)$  with  $f_{0r}$ 's within  $wf_{0rdata}$  of  $f_{0rdata}$ .
- For example, if we use w=10%, then we're conditioning on  $f_0$  being between 90% and 110% of  $f_{0rdata}$ .
- Our p-value is:  $\sum_{LR(x_1,x_2) \ge LRdata, |f0r(x_1,x_2)-f0data| < wf0data} P(x_1,x_2|f_{0rdata}) / \sum_{|f0r(x_1,x_2)-f0rdata| < wf0rdata} P(x_1,x_2|f_{0rdata}).$
- With the test data, the p-value is 0.2338813.
- Again, each possible data set has its own  $f_{0r}$ , so each data set gets its own p-value based on its own distribution under the null.

### The cumulative density function

- This is the distribution of the p-value if the null is true and  $f_{0r}$  is the data's  $f_{0r}$ .
- The c.d.f. for this pvalue is a lot closer to what it should be.



## Focusing on practical $\alpha$

- We can still see the discretization, but it's not as bad.
- Even though f<sub>0r</sub> is not a sufficient statistic, conditioning still seems to work.



### Conclusions

- Maximum likelihood seemed despite the background events.
- Conditional inference looked more consistent than unconditional inference.
- When designing an ad hoc test statistic, check the distribution of the resulting p-value.

### Future work

- Here the conditioning window grew as f<sub>0</sub> grew. Do I do better or different with a fixed window width?
- The MLEs for  $f_{0r}$ ,  $f_{1r}$  and  $f_{2r}$  are all biased. Does this bias create problems?
- As the arrays are open longer,  $\mu_{1f}$  and/or  $\mu_{2f}$  increase.
  - We really start with frequencies  $f_{1f}$  and  $f_{1f}$  for background events, and then get  $\mu_{1f}=T_1f_{1f}$  and  $\mu_{2f}=T_2f_{2f}$ .
  - How large do  $T_1$  and  $T_2$  have to be to yield a test with reasonable power?
- At what point can we discard the exact test and switch to asymptotics?

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